



# A Mixed Formulation For The Fractional Poisson Problem

Nahuel de León<sup>a</sup> in a joint work with Wilfredo Angulo<sup>b</sup> and Juan Pablo Borthagaray<sup>a</sup>

PEDECIBA. Universidad de la República, Uruguay.<sup>a</sup>  
Facultad de Ciencias Exactas y Naturales, PUCE, Ecuador.<sup>b</sup>



## Abstract

In this work we explore a mixed formulation of the fractional Poisson problem via the fractional divergence and fractional gradient. Following Hughes and Masud [1] we pursue a stabilized formulation that results in a coercive and well-posed problem. We prove the convergence of this discretization, its order and perform some numerical experiments.

## Fractional Gradient and Fractional Divergence

### Definition

Following [2], the fractional gradient and divergence can be expressed in integral form as:

$$\begin{aligned}\mathbf{grad}^s \varphi(x) &= \mu(d, s) \int_{\mathbb{R}^d} \frac{(y-x)(\varphi(y) - \varphi(x))}{|y-x|^{d+s+1}} dy, \\ \operatorname{div}^s \Phi(x) &= \mu(d, s) \int_{\mathbb{R}^d} \frac{(y-x) \cdot (\Phi(y) - \Phi(x))}{|y-x|^{d+s+1}} dy,\end{aligned}$$

where the normalization constant is given by

$$\mu(d, s) = \frac{2^s \Gamma\left(\frac{d+s+1}{2}\right)}{\pi^{d/2} \Gamma\left(\frac{1-s}{2}\right)}.$$

## Problem Formulation

Let  $\Omega \subset \mathbb{R}^d$  be a bounded and Lipschitz domain. We consider the following fractional Darcy problem: find  $(p, \Phi) \in L^2(\Omega) \times H(\operatorname{div}^s; \Omega)$  such that

$$\begin{cases} \Phi + \mathbf{grad}^s p = 0 & \text{in } \mathbb{R}^d, \\ \operatorname{div}^s \Phi = f & \text{in } \Omega, \\ p = 0 & \text{in } \Omega^c, \end{cases}$$

where

$$H(\operatorname{div}^s; \Omega) := \{\Psi \in L^2(\mathbb{R}^d, \mathbb{R}^d) : (\operatorname{div}^s \Psi)|_{\Omega} \in L^2(\Omega)\},$$

furnished with the norm

$$\|\Psi\|_{H(\operatorname{div}^s; \Omega)} := \left( \|\Psi\|_{L^2(\mathbb{R}^d)}^2 + \|(\operatorname{div}^s \Psi)|_{\Omega}\|_{L^2(\Omega)}^2 \right)^{1/2}.$$

We also denote by  $\tilde{L}^2(\Omega)$  the space of  $L^2(\Omega)$  that are extended by zero to  $\mathbb{R}^d$ .

The weak formulation of the problem reads: find  $(p, \Phi) \in \tilde{L}^2(\Omega) \times H(\operatorname{div}^s; \Omega)$  such that, for all  $(q, \Psi) \in \tilde{L}^2(\Omega) \times H(\operatorname{div}^s; \Omega)$ ,

$$\int_{\mathbb{R}^d} \Phi \cdot \Psi - \int_{\mathbb{R}^d} p \operatorname{div}^s \Psi + \int_{\mathbb{R}^d} q \operatorname{div}^s \Phi = \int_{\mathbb{R}^d} f q. \quad (1)$$

Note that all but the first of the integrals above need to be effectively computed in  $\Omega$ .

We are using the integration by parts formula:

$$\int_{\mathbb{R}^d} \mathbf{grad}^s q \cdot \Psi = - \int_{\mathbb{R}^d} q \operatorname{div}^s \Psi, \quad \text{for all } q \in \tilde{H}^s(\Omega) \text{ and } \Psi \in H(\operatorname{div}^s; \Omega).$$

## Well-Posedness

Let

$$\begin{aligned}a: H(\operatorname{div}^s; \Omega) \times H(\operatorname{div}^s; \Omega) &\rightarrow \mathbb{R}, & a(\Phi, \Psi) &= \int_{\mathbb{R}^d} \Phi \cdot \Psi, \\ b: \tilde{L}^2(\Omega) \times H(\operatorname{div}^s; \Omega) &\rightarrow \mathbb{R}, & b(q, \Psi) &= \int_{\Omega} q \operatorname{div}^s \Psi, \\ F: \tilde{L}^2(\Omega) &\rightarrow \mathbb{R}, & F(q) &= \int_{\Omega} f q.\end{aligned} \quad (2)$$

Problem (1) is well-posed if

- I the form  $a$  is coercive in  $\ker B$ , the Riesz representative of the map  $b(\cdot, \Psi)$ ;
- II the form  $b$  satisfies an inf-sup condition.

## Stabilized Form

To shorten the notation, we define in  $(\tilde{L}^2(\Omega) \times H(\operatorname{div}^s; \Omega)) \times (\tilde{L}^2(\Omega) \times H(\operatorname{div}^s; \Omega))$  the form

$$\mathcal{L}((p, \Phi), (q, \Psi)) := a(\Phi, \Psi) - b(p, \Psi) + b(q, \Phi).$$

Let  $\mathbb{V} := \tilde{H}^s(\Omega) \times H(\operatorname{div}^s; \Omega)$ . We introduce the stabilized form in  $\mathbb{V} \times \mathbb{V}$ :

$$\mathcal{L}_{\text{stab}}((p, \Phi), (q, \Psi)) := \mathcal{L}((p, \Phi), (q, \Psi)) + \frac{1}{2} \int_{\mathbb{R}^d} (\Phi + \mathbf{grad}^s p) \cdot (-\Psi + \mathbf{grad}^s q). \quad (3)$$

With this, we consider the stabilized problem: find  $(p, \Phi) \in \mathbb{V}$  such that

$$\mathcal{L}_{\text{stab}}((p, \Phi), (q, \Psi)) = F(q) \quad \forall (q, \Psi) \in \mathbb{V}.$$

We introduce a norm in  $\mathbb{V}$ :

$$\| (q, \Psi) \| := \left[ \frac{1}{2} (\|\mathbf{grad}^s q\|_{L^2(\mathbb{R}^d)}^2 + \|\Psi\|_{L^2(\mathbb{R}^d)}^2) \right]^{1/2}.$$

## Coercivity/Stability, Continuity and Well-Posedness

We have

$$\begin{aligned}\mathcal{L}_{\text{stab}}((p, \Phi), (p, \Phi)) &= \| (p, \Phi) \|^2 \quad \forall (p, \Phi) \in \mathbb{V}, \\ \mathcal{L}_{\text{stab}}((p, \Phi), (q, \Psi)) &\leq \| (p, \Phi) \| \| (q, \Psi) \| \quad \forall (p, \Phi), (q, \Psi) \in \mathbb{V}.\end{aligned}$$

As usual, the Lax-Milgram theorem gives rise to the well-posedness of our problem.

## Finite Element Discretization

We are approximating  $\Phi$ , which is not compactly supported, and the form  $a$  in (2) and the stabilization term in (3) involve integration in  $\mathbb{R}^d$ . To tackle this problem, we consider a ball  $B_H$  containing  $\Omega$  and such that  $H := d(\Omega, B_H^c) \gg 1$ .

Let  $\{\mathcal{T}_h\}_{h>0}$  be a family of **regular**, simplicial triangulations of  $\overline{B_H}$  with mesh size  $h > 0$ . Moreover, we assume that  $\{T \in \mathcal{T}_h : T \cap \Omega \neq \emptyset\}$  is a triangulation of  $\Omega$  for all  $h > 0$ . On the triangulation  $\mathcal{T}_h$  we define

$$\mathbb{V}_h = \{(q_h, \Psi_h) \in \mathcal{P}_1(\mathcal{T}_h) \times \mathcal{P}_1^d(\mathcal{T}_h) : q_h|_{\Omega^c} = 0, \Psi_h|_{B_H^c} = 0\}.$$

We consider the following discrete problem: find  $(p_h, \Phi_h) \in \mathbb{V}_h$  such that

$$\mathcal{L}_{\text{stab}}((p_h, \Phi_h), (q_h, \Psi_h)) = F(q_h) \quad \forall (q_h, \Psi_h) \in \mathbb{V}_h. \quad (4)$$

## Galerkin Orthogonality

The fact that  $\mathbb{V}_h \subset \mathbb{V}$  implies the existence and uniqueness of solutions to (4). Let  $(p, \Phi) \in \mathbb{V}$  and  $(p_h, \Phi_h) \in \mathbb{V}_h$  be the exact solution and the discrete solution, respectively. Then, we have the Galerkin orthogonality:

$$\mathcal{L}_{\text{stab}}((p - p_h, \Phi - \Phi_h), (q_h, \Psi_h)) = 0 \quad \forall (q_h, \Psi_h) \in \mathbb{V}_h.$$

Therefore,

$$\| (p - p_h, \Phi - \Phi_h) \| \leq \inf_{(q_h, \Psi_h) \in \mathbb{V}_h} \| (p - q_h, \Phi - \Psi_h) \|.$$

## Order of Convergence

To obtain **convergence rates**, we employ regularity estimates up to  $\partial\Omega$  for the fractional Poisson problem [3], regularity estimates for the flux given by the mapping properties of the  $\mathbf{grad}^s$  operator [4] and quasi-interpolation estimates (cf., [5] and [6]): We have

$$\| (p - p_h, \Phi - \Phi_h) \| \leq \begin{cases} Ch^{\frac{1}{2}} |\log h|^{\frac{1}{2}} \|f\|_{L^2(\Omega)}, & \text{for } s > 1/2, \\ Ch^s |\log h|^{\frac{1}{2}} \|f\|_{L^2(\Omega)}, & \text{for } s < 1/2, \\ Ch^{\frac{1}{2}} |\log h| \|f\|_{L^2(\Omega)}, & \text{for } s = 1/2. \end{cases}$$

## Numerical Experiments

We test the convergence rates for different values of  $s$  in 1d. We take  $f \equiv 1$ ,  $\Omega = (-1, 1)$  and the distance  $H = d(B_H^c, \Omega)$  is chosen such that  $H^{-1-d-2s} \simeq h |\log h|$ .

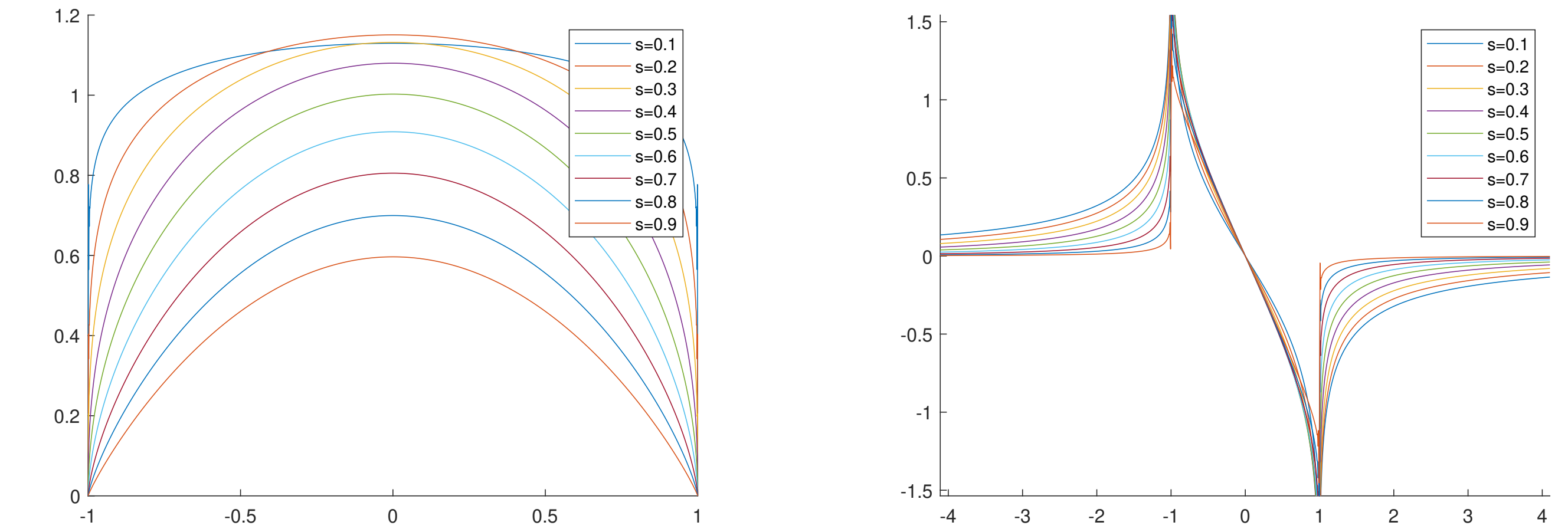


Figure: Computed pressures for different values of  $s$ .

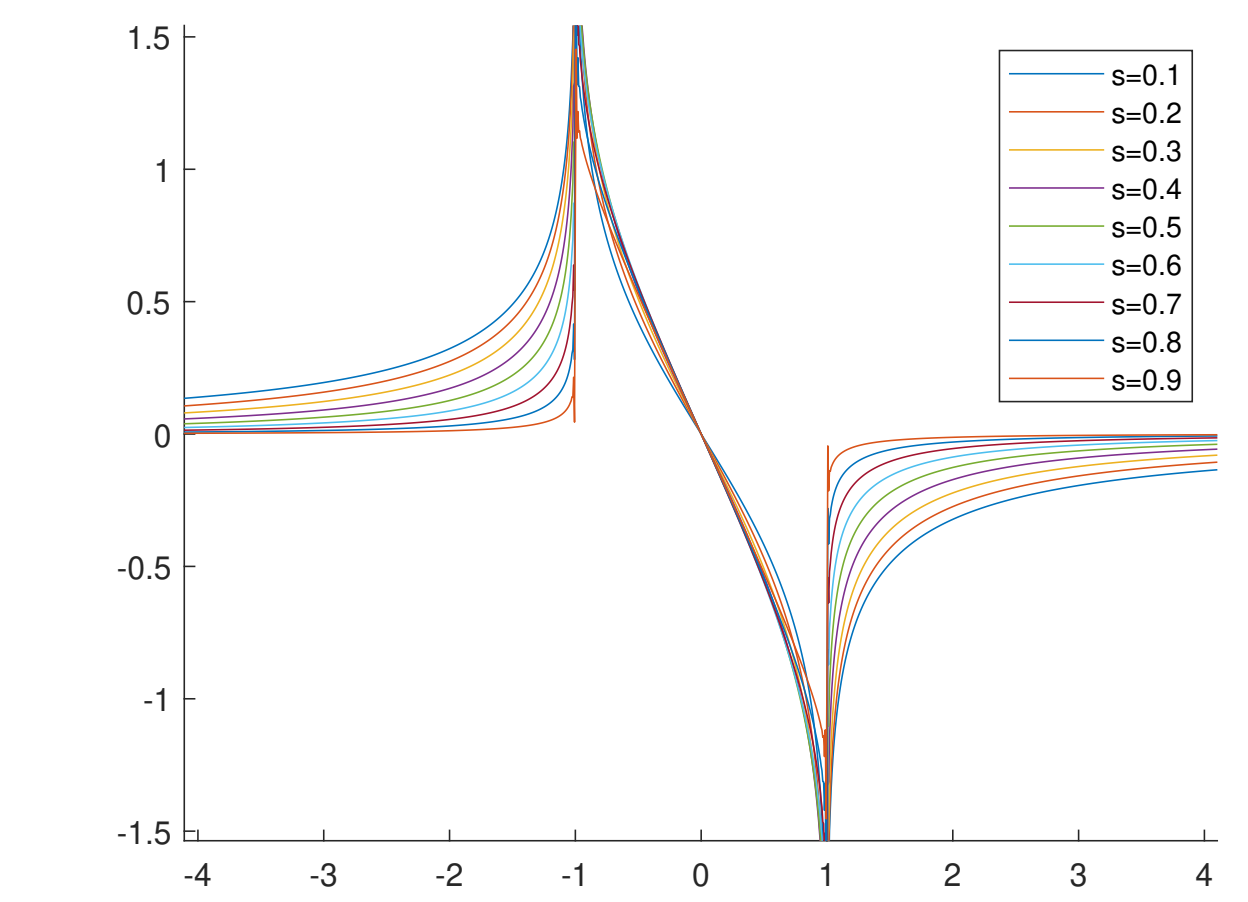


Figure: Computed fluxes for different values of  $s$ .

Value of s	$H^s$ order	$L^2$ order	Value of s	$H^s$ order	$L^2$ order
0.1	0.4691	0.4949	0.6	0.5005	0.9966
0.2	0.4956	0.6444	0.7	0.5009	0.9928
0.3	0.5000	0.7968	0.8	0.5014	0.9952
0.4	0.5004	0.9236	0.9	0.5017	1.0045
0.5	0.5005	1.0012			

Table: Order of convergence for the pressure  $p$ .

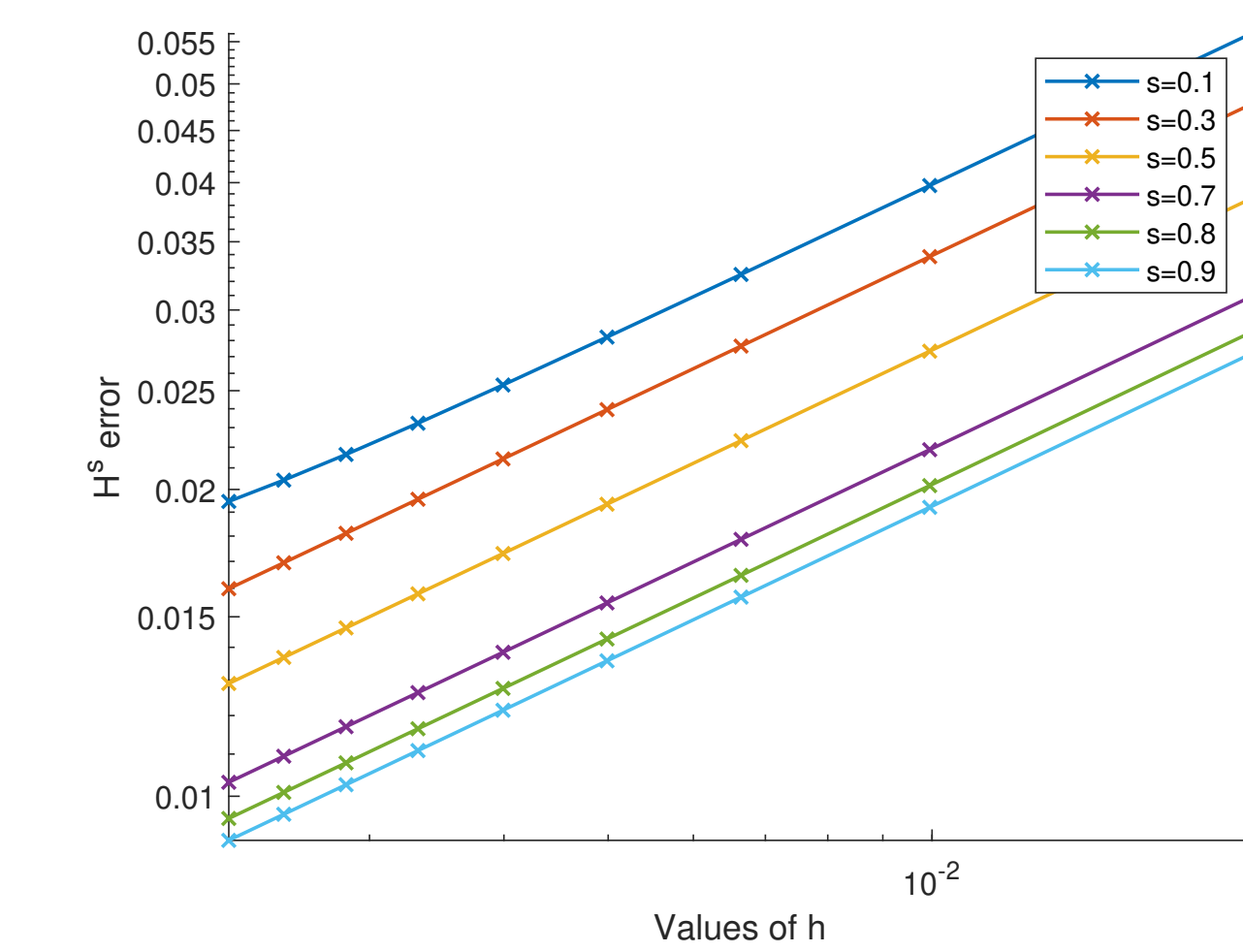


Figure: Error in  $H^s$  vs  $h$ .

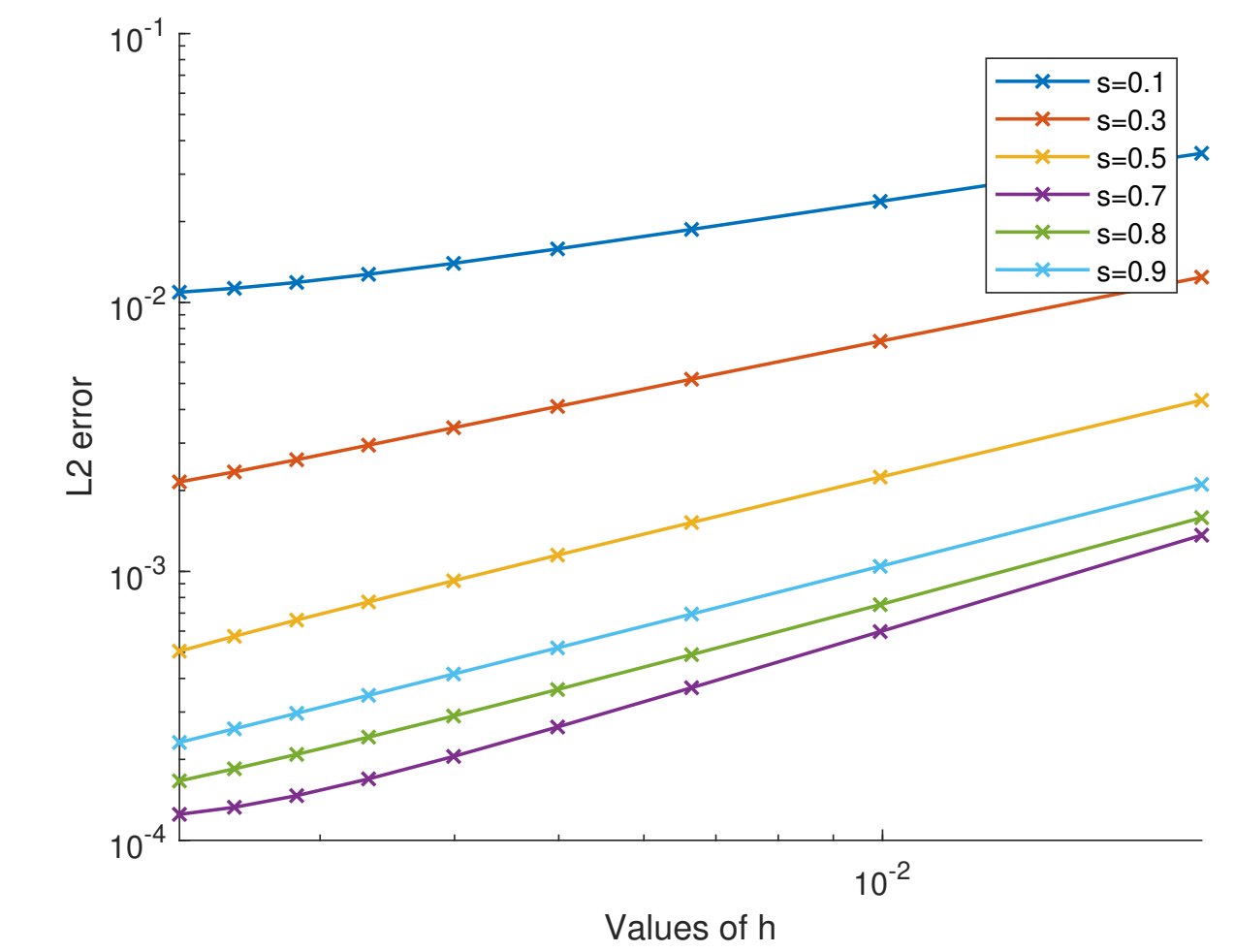


Figure: Error in  $L^2$  vs  $h$ .

## Work in progress and questions

- 2d implementation.
- Non-zero Dirichlet conditions, and Neumann conditions.
- Convergence rates in non-uniform meshes.
- Test  $(\mathcal{P}_0)$  elements for the pressure  $p$ .

## References

- [1] A. Masud and T. J. R. Hughes, "A stabilized mixed finite element method for darcy flow," *Computer Methods in Applied Mechanics and Engineering*, vol. 191, no. 39-40, pp. 4341-4370, 2002.
- [2] G. E. Comi and G. Stefani, "A distributional approach to fractional sobolev spaces and fractional variation: existence of blow-up," *Journal of Functional Analysis*, vol. 277, no. 10, pp. 3373-3435, 2019.
- [3] J. P. Borthagaray and R. H. Nochetto, "Besov regularity for the dirichlet integral fractional laplacian in lipschitz domains," *Journal of Functional Analysis*, vol. 284, no. 6, p. 33, 2023.
- [4] M. D'Elia, M. Gulian, H. Olson, and G. E. Karniadakis, "Towards a unified theory of fractional and nonlocal vector calculus," *Fractional Calculus and Applied Analysis*, vol. 24, pp. 1301-1355, 2021.
- [5] Z. Chen and R. H. Nochetto, "Residual type a posteriori error estimates for elliptic obstacle problems," *Numerische Mathematik*, vol. 84, pp. 527-548, 2000.
- [6] J. P. Borthagaray, R. H. Nochetto, and A. J. Salgado, "Weighted sobolev regularity and rate of approximation of the obstacle problem for the integral fractional laplacian," *Mathematical Models and Methods in Applied Sciences*, vol. 29, no. 14, pp. 2679-2717, 2019.