

Nonlinear wave propagation through multiple scattering media and virtual time reversal focusing

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1 In this work, the propagation of an ultrasonic nonlinear wave through a multiple
2 scattering medium is experimentally studied. The interaction between multiple scat-
3 tering and nonlinear phenomena is analyzed by the cross correlation of the scattered
4 field. This approach corresponds to a virtual time reversal. The cross correlated field
5 is focused in both time and space. In linear regime, it is known that the focal width
6 decreases as the thickness of the multiple scattering medium is increased. In this
7 work, it is shown that this behavior is followed by a nonlinear wave and its harmon-
8 ics. Moreover, due to the spectral richness of the nonlinear wave, the focal width
9 is reduced in the nonlinear regime. This fact allows concluding that the harmonics
10 propagate following a linear scattering equation, although a nonlinear regime is re-
11 quired to generate them. Beside the experimental work, an estimation of the order
12 of magnitude of the parameters that quantify nonlinearity and scattering phenomena
13 is performed. The estimation shows that the Lighthill-Westervelt equation is as an
14 accurate theoretical model for describing the multiple scattering of a nonlinear wave
15 in the experiments.

16 **I. INTRODUCTION**

17 The scattering phenomena are an important subject in acoustics. From metal crack de-
18 tection to imaging in medicine, wave propagation in non-homogeneous media becomes an
19 important topic on non-invasive techniques¹. Some studies on multiple scattering of ultra-
20 sonic waves were carried out on two-dimensional media, consisting of a random collection
21 of parallel rods submerged in water^{2,3}. This kind of media can be easily assembled and its
22 construction allows changing some parameters (as the thickness or the scatterers density)
23 in a simple way. Moreover, a single configuration of disorder as well as an ensemble average
24 (coherent wave) of acoustic waves can be studied. A reference work was published by A.
25 Tourin et al., where some experimental methods to characterize a two-dimensional sample
26 in terms of transport parameters are described³. In their paper, the authors describe an
27 experiment to measure the coherent field of a scattered wave. This measure allows comput-
28 ing the elastic mean free path, parameter related to the density of scatterers and their cross
29 section. A similar procedure was followed by N. Viard et al. to study the interaction of a
30 shock wave with a multiple scattering medium⁴. Nonlinear waves have a particular charac-
31 teristic: the generation of harmonics. This implies that a wave with central frequency f_0 will
32 generate, as it propagates, spectral components at frequencies multiples of f_0 . Taking this
33 into account, Viard et al. studied the coherent field of a nonlinear wave which traverses a
34 multiple scattering medium. The authors measured the elastic mean free path of the spectral
35 components present in the wave. They conclude that, under their experimental conditions,
36 both nonlinear phenomena and multiple scattering phenomena do not interact.

37 The estimation of the coherent field implies an average of the acoustic field over different
38 configurations of disorder (ensemble average). In this work, an alternative approach is
39 proposed. The whole wave -including the coda wave- is studied by the cross correlation of
40 the field which has traversed a single configuration. This procedure corresponds to a virtual
41 time reversal.

42 The time reversal process has been widely studied and applied in various acoustical
43 systems. In the linear regime, it has been studied by M. Fink since the 90's^{5,6}. The time
44 reversal process is able to focus the acoustic energy in both space and time. This property
45 allows getting very high amplitude focused waves when is applied to devices like waveguides⁷
46 or resonant cavities^{8,9}. Moreover, the time reversal process is able to focus waves through
47 multiple scattering media. In a linear regime, it was shown that the focal spot width
48 decreases the greater the thickness of the medium¹⁰.

49 In a nonlinear regime, the time reversal process in a homogeneous medium has been
50 studied experimentally by M. Tanter et al.¹¹, showing that a nonlinear wave is invariant
51 under a time inversion if it propagates a distance lower than the distance where the shock
52 wave occurs. In their work, the authors point out the difficulty of carrying out the experiment
53 because the acoustic energy of a nonlinear wave is distributed into harmonics. Therefore,
54 a device with very large bandwidth is required. Piezoelectric transducers are unable to
55 properly emit the higher harmonics. Therefore, the authors figured out an experimental
56 setup, which implies the reflection of waves to avoid the re-emission of the reversed wave
57 from the transducer.

58 The difficulty pointed out by Tanter et al. can be avoided by performing a virtual time
59 reversal process, because the harmonics are present in the cross correlated field. Then, we
60 proceed in this way to analyze the coupling between nonlinear and scattering phenomena.
61 The main point of the work is centered on determining the spatial focal width at -3 dB
62 as a function of the thickness of the multiple scattering medium. The results obtained are
63 compared with already known results of the linear theory and the behavior of the harmonics
64 present in the scattered wave is characterized. The work is organized as follows: in section
65 II the experimental setup together with the features of the multiple scattering medium are
66 described and in section III an appropriate theoretical model of scattering for the experi-
67 ments is briefly described. Then, based on the estimation of the orders of magnitude of the
68 parameters involved, a conclusion about the interaction between scattering and nonlinearity
69 is sketched out. The theoretical approach is verified experimentally from section IV. In this
70 section, the characteristics that evidence the nonlinear regime of the scattered waves are
71 presented. Those are: the generation of harmonics, typical nonlinear phenomenon and their
72 presence in the coda signal, characteristic of the multiple scattering. Moreover, a study of
73 the coherent field, the harmonics present in it and its interaction with multiple scattering
74 is presented. The results gave us the motivation for performing a different experiment in-
75 volving the whole wave and not only the coherent field: the virtual time reversal, which is
76 presented in section V.

77 **II. EXPERIMENTAL SETUP**

78 The experiments of this work are carried out over the setup shown in figure 1. A multiple
 79 scattering medium is positioned between a flat circular transducer (nominal diameter $\phi =$
 80 28.757 mm, central frequency $f_0 = 1$ MHz) and a needle hydrophone (Onda HNA-0400)
 81 immersed in degassed water (sound speed $c_w = 1.5$ mm μs^{-1} and density $\rho_w = 1.00$ g cm^{-3}).
 82 The degassing process avoid the formation of cavitation bubbles. The transducer is excited
 83 with five cycles of a 1 MHz sinusoidal signal generated with a function generator (Tektronix
 84 AFG 3021B) and magnified through a 50 dB gain RF power amplifier (E&I A075). The
 85 amplitude of the output voltage from the amplifier varies between 32 V and 285 V. This
 86 amplitude is referred to as *applied voltage* and is noted as V_{in} . The hydrophone is placed

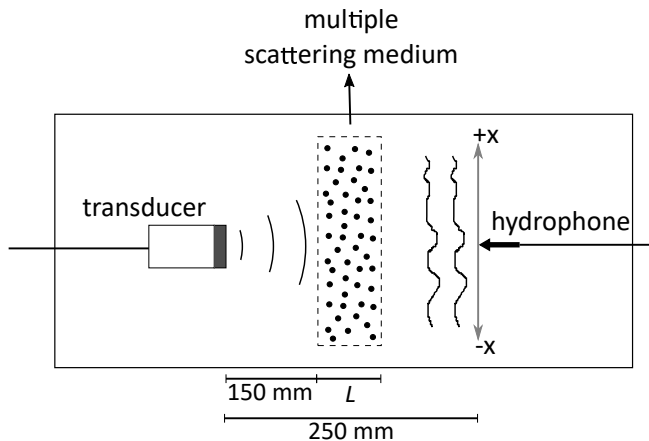


FIG. 1. The system consists of a transducer and a hydrophone immersed in water and 250 mm apart. Between them (at 150 mm from the transducer) is placed a multiple scattering medium of thickness L composed of randomly distributed vertical copper rods. The transducer is excited with a five-cycle sinusoidal signal at 1 MHz. The generated wave is acquired by the hydrophone at positions along the x -axis.

87 250 mm far from the transducer and with a stepper motor (minimum step 0.254 mm) it is
 88 positioned at different points in the x -axis defined in figure 1. In the position $x = 0$ the
 89 hydrophone is in front of the transducer.

90 The multiple scattering medium is a slab composed of parallel copper cylinders (sound
 91 speed $c_c = 3.6 \text{ mm } \mu\text{s}^{-1}$ and density $\rho_c = 8.96 \text{ gcm}^{-3}$), nominal diameter 0.7 mm and effective
 92 length 120 mm. The cylinders are randomly positioned on a grid of length 140 mm (measured
 93 parallel to the x -axis) and thickness L , where the minimum distance between two cylinders
 94 is 2.5 mm. Of the available grid points, three quarters are filled with cylinders. With
 95 this configuration, the ratio between the area occupied by the cylinders and the total area
 96 occupied by the slab is, on average, $a_c = 0.0462$, while the ratio between the area occupied
 97 by water and the total area is $a_w = 0.9538$. The experiments are performed by changing the
 98 thickness of the slab between $L = 8 \text{ mm}$ and $L = 60 \text{ mm}$.

99 Experimentally, we found that the maximum pressure amplitude of the fundamental
 100 frequency is reached at a distance of 130 mm far from the transducer, while the maximum
 101 pressure amplitude of the second harmonic frequency (generated by nonlinear effects) is
 102 reached at 180 mm. With this data, it is convenient to place the multiple scattering medium
 103 at a distance of 150 mm from the transducer where the first and second harmonics reach a
 104 high amplitude (less than 1 dB below their respective maximum level).

105 The Mach number ϵ is useful to quantify the order of magnitude of nonlinear phenomena.
 106 This number results from the ratio between the particular velocity of the wave on the surface
 107 of the source and the propagation speed. Assuming that the pressure p_s and the velocity
 108 v_s on the source surface are related as $p_s = c_0 \rho_0 v_s$, the Mach number can be obtained as

109 $\epsilon = \frac{p_s}{\rho_0 c_0^2}$. With a measurement of the acoustic field at 130 mm far from the transducer
 110 (where the maximum pressure amplitude is reached) and assuming that the pressure in the
 111 transducer face is half this value (as in the linear field of a circular aperture¹²), the order of ϵ
 112 can be estimated. For $V_{in} = 32$ V the order of ϵ is 10^{-6} and for $V_{in} = 285$ V the order is 10^{-5} .
 113 The Mach number is also useful to estimate the shock formation distance l_s where a plane
 114 wave turns into a shock wave, related to the wave number k and the nonlinear parameter β
 115 as $l_s = (\beta k \epsilon)^{-1}$. Taking $\beta = 3.5$ for water⁴, the shock distance is in the order of magnitude
 116 of 10^3 mm, far away from the free propagation distances of the wave (250 mm).

117 III. THE SCATTERING MODEL. A SIMPLE THEORETICAL APPROACH.

118 In this work, the interaction between the nonlinear wave and the multiple scattering
 119 medium is studied experimentally. However, some properties can be inferred from a theo-
 120 retical model. Nonlinear scattering phenomena in a non dissipative media can be modeled
 121 by the generalized Lighthill-Westervelt equation¹³:

$$\left(\nabla^2 - \frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} \right) p - \frac{\nabla \rho_0}{\rho_0} \cdot \nabla p = - \frac{\beta}{\rho_0 c_0^4} \frac{\partial^2 p^2}{\partial t^2} \quad (1)$$

122 where p represents the acoustic pressure, $c_0 = c_0(\mathbf{r})$ and $\rho_0 = \rho_0(\mathbf{r})$ are the wave speed
 123 and the medium density, respectively. The last two magnitudes have a spatial dependence
 124 due to the inhomogeneities introduced by the slab. The parameter $\beta = \beta(\mathbf{r})$ quantifies the
 125 nonlinearity of the propagation medium and also depends on the spatial coordinate.

126 The validity of equation 1 requires some hypothesis about the order of magnitude of the
 127 variables involved. On one hand, the order of magnitude of nonlinear phenomena can be

128 quantified through the square of the Mach number defined in II. On the other hand, multiple
 129 scattering phenomena are of the order of¹³

$$\eta = \left| \frac{c_0 - \bar{c}_0}{\bar{c}_0} \right| \quad (2)$$

130 where \bar{c}_0 is the spatial average of the propagation speed. Finally, equation 1 is valid if the
 131 product $\eta\epsilon^2$ is much smaller than η and ϵ^2 .

132 In section II, the sound speed of water and copper together with the ratios a_c and a_w were
 133 given. Considering these values, an average speed \bar{c}_0 can be computed as $\bar{c}_0 = a_c c_c + a_w c_w$.
 134 With this calculation and the equation 2 where c_0 is substituted by c_w , the order of magnitude
 135 for the scattering phenomena yields $\eta \approx 10^{-2}$. Therefore, the order of $\eta\epsilon^2$ is 10^{-12} , wich
 136 means that the system verifies the hypotheses required by the theoretical model.

137 An observation can be made based on the estimated orders of magnitude. The wave
 138 initially propagates 150 mm in water. In this path, the wave propagation is described by
 139 the usual Westervelt equation ($\frac{\nabla \rho_0}{\rho_0} = 0$ in equation 1). The nonlinear propagation implies
 140 the generation of harmonics of higher order than the fundamental. When the nonlinear wave
 141 impinges the multiple scattering medium, the order of η is greater than ϵ^2 . This allows to
 142 neglect the term on the right side in equation 1 and the propagation of the wave in the slab
 143 is described by a linear scattering equation. This fact suggest that the harmonics propagate
 144 following a linear scattering equation, regardless if they have been generated by nonlinear
 145 effects or not. This shows that there is no interaction between nonlinear phenomena and
 146 multiple scattering. In this case, it is said that these phenomena are decoupled. In sections
 147 IV and V, an experimental analysis is performed, which allows to contrast this theoretical
 148 statement.

149 **IV. THE NONLINEAR SCATTERED WAVE**

150 **A. Harmonics in the coda wave**

151 The properties of the nonlinear scattered waves are analyzed by measuring the acoustic
 152 wavefield at $x = 0$. These measurements are shown in figure 2. The scattered waves of
 153 figures 2a and 2b, traverse slabs of thicknesses $L = 38, 15$ mm, respectively, and they were
 154 acquired by exciting the transducer with $V_{in} = 285$ V ($\epsilon \approx 10^{-5}$). These waves have a longer

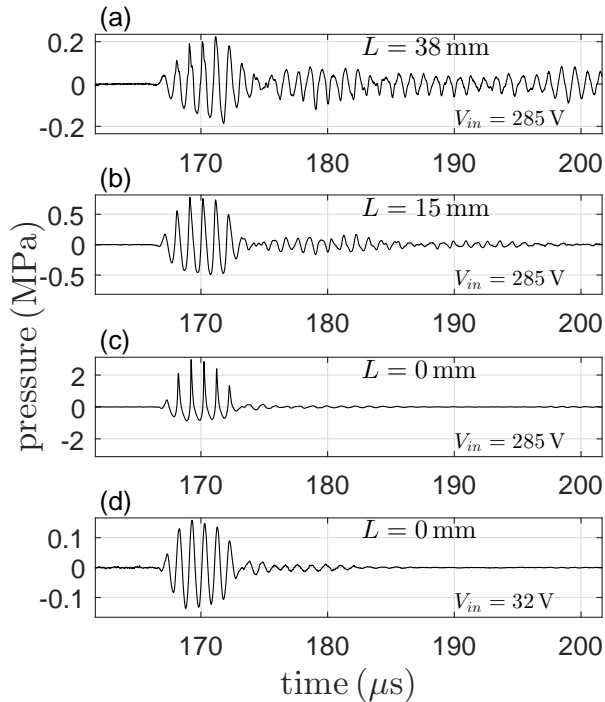


FIG. 2. Temporal waveforms acquired at $x = 0$. The waves traverse slabs of (a) $L = 38$ mm, (b) $L = 15$ mm and (c) $L = 0$ mm (the latter is not scattered). The voltage amplitude is $V_{in} = 285$ V. (d) Non scattered wave acquired with $V_{in} = 32$ V. As L increases the shock-wave trace is less noticeable. The same happens with a lower voltage amplitude ($V_{in} = 32$ V).

155 duration than the initial excitation ($5 \mu s$), because part of them are delayed by multiple
 156 reflections that occurs in the slab. This part is known as the *coda wave*^{2,3}. The wave in
 157 figure 2c is not scattered ($L = 0$) and it was acquired with the same voltage. It exhibits
 158 a shock-wave trace due to the nonlinear harmonics of higher order than the fundamental
 159 one. The non-scattered linear wave of figure 2d, acquired with $V_{in} = 32 \text{ V}$ ($\epsilon \approx 10^{-6}$) do not
 160 show this trace. Moreover, this trace disappears progressively if the thickness of the slab
 161 is increased. To better understand this fact, the spectra of the nonlinear waves are shown
 162 in figure 3a. The intensity level is represented in a dB scale computed from the spectral
 163 amplitude obtained from a FFT algorithm. The reference (0 dB) is the maximum level of the
 164 spectrum of the non scattered wave (around 1 MHz). The waves have a spectral component
 165 at the central frequency (1 MHz) but also exhibits the components at the frequencies of
 166 its harmonics. Although the harmonics are recognizable in the three signals, the intensity
 167 level of each harmonic decreases when the slab is introduced. Moreover, the level of the
 168 harmonics decays respect to the fundamental one with each slab, causing the loss of the
 169 shock-wave trace pointed before. For example, the difference of the intensity level between
 170 the fundamental harmonic and the second one is of 5 dB without the slab and increases to
 171 15 dB for the 38 mm thickness slab.

172 The harmonics contained in the coda waves of figure 2, can be better analyzed by including
 173 the time variable, as was done in the spectrograms of figures 3b to 3d. They were computed
 174 by splitting the whole signal into Hamming windows of $5 \mu s$ and performing a FFT. The
 175 color scale of the images is in dB, being the reference the maximum amplitude obtained in
 176 each spectrogram. In figure 3d, where there is no scattering, the harmonics are concentrated

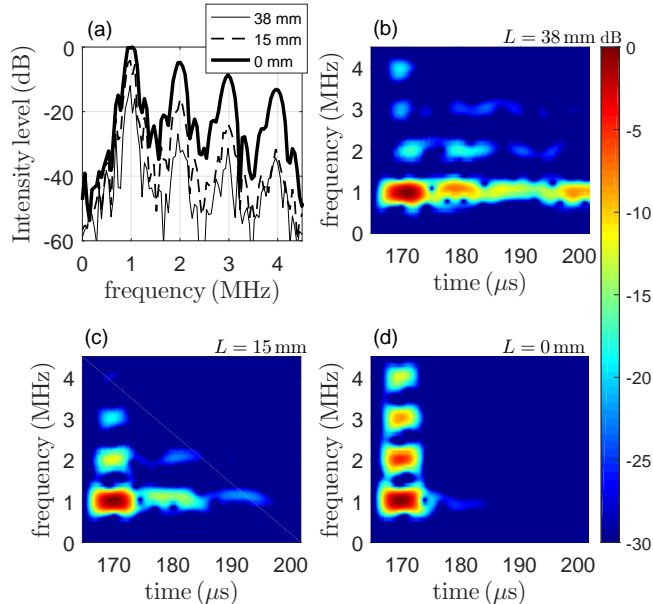


FIG. 3. Color online. (a) Spectra of the waves that traverse slabs of thickness 38 mm (thin line), 15 mm (dashed line) and a non scattered wave (thick line). For the three cases, different harmonics are presented in the wave, but they show a significant decay as the thickness of the slab is increased. (b) Spectrogram of the wave that traverses a 38 mm thickness slab. (c) Spectrogram of the wave that traverses a 15 mm thickness slab. (d) Spectrogram of the non scattered wave. The maximum amplitude of the harmonics in the non-scattered wave are concentrated at the arrival time. As the slab thickness is increased, the harmonics spread into the coda wave.

177 around $170 \mu s$ (arrival time). With a slab of thickness $L = 15 \text{ mm}$ (fig. 3c), the fundamental
 178 harmonic and the second harmonic spreads over the coda wave and, with a 38 mm thickness
 179 slab (fig. 3b), the third harmonic is also seen spreading over the coda wave.

180 The measurements presented in this section, show that the high amplitude of the waves
 181 can generate nonlinear effects, even if they traverse the multiple scattering medium. Fur-
 182 thermore, the harmonics spread over the coda wave. Then, the multiple scattering has an

183 effect over the nonlinear harmonics. The experimental study of this effect begins in the next
 184 subsection by first studying the coherent field of the wave.

185 **B. The coherent wave**

186 The coherent field is studied by reproducing the Viard's experiment⁴. The spectrum of
 187 the coherent field is computed and the level of the harmonics are analyzed as a function of L .
 188 In a linear regime, the intensity level (in a dB scale) of the spectral components should decay
 189 linearly as $-L/l_e$, where l_e is the elastic mean free path, a frequency-dependent parameter³.

190 An estimation of the coherent field is performed by averaging signals acquired in different
 191 disorder configurations^{3,4}. To achieve this, the position of the slab is changed 0.762 mm
 192 parallel to x -axis. In this way, 80 signals are recorded for averaging (avoiding being close
 193 to the border of the slab).

194 In figure 4a, the intensity level of the first harmonic is plotted in a dB scale (being
 195 the reference the amplitude of its harmonic at $L = 0$) against L . Two data series are
 196 compared: with $V_{in} = 32 V$, where a linear regime can be considered ($\epsilon \approx 10^{-6}$) and with
 197 $V_{in} = 285 V$, where the regime is non linear ($\epsilon \approx 10^{-5}$). Notice that, in both cases, the
 198 intensity level decreases linearly as the slab thickness increase. In addition, by performing
 199 a linear fitting, the elastic mean free path is calculated in each case. The values obtained
 200 are (9.72 ± 0.34) mm in linear regime and (9.90 ± 0.33) mm in nonlinear regime. Taking
 201 into account the uncertainty, these values are equal with each other. In a similar way the
 202 amplitude of the second harmonic is studied. In figure 4b the decay of its intensity level is
 203 plotted against L . The nonlinear data was obtained with a voltage $V_{in} = 285 V$. As can

204 be seen in the figure, its intensity level also decreases linearly with L . In linear regime the
 205 measure can not be achieved with this system. Instead, the transmitter is changed by a
 206 low-power transducer whose central frequency is 2.25 MHz and its bandwidth has a good
 207 response at 2 MHz. By exciting the transducer with a 2 MHz signal, a linear decay is

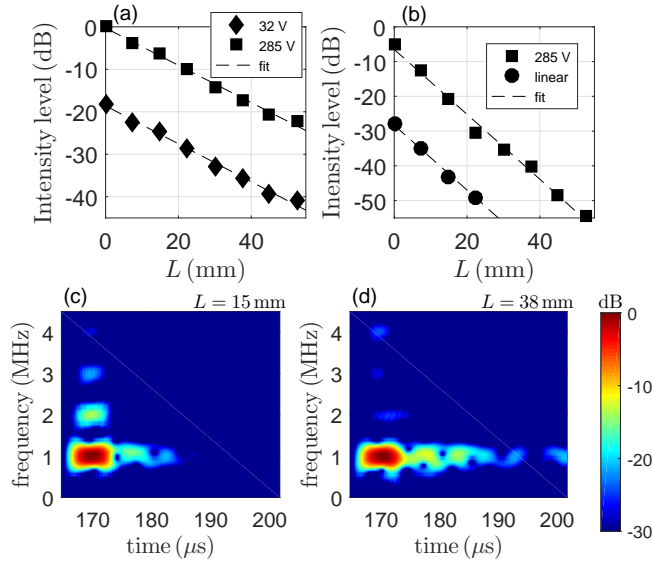


FIG. 4. Color online. (a) Intensity level in dB of the fundamental harmonic of the coherent wave as a function of L . For $V_{in} = 32 V$ (diamonds) the the regime is linear and for $V_{in} = 285 V$ (squares), nonlinear. (b) Intensity level of the second harmonic of the coherent wave against L . The circles represent the intensity level of the wave emmitted by a linear transducer at 2 MHz. The dotted line is a linear fit on each data set. (c) Spectrogram of the coherent field of a nonlinear wave that is scattered by a 15 mm thickness slab. (d) The same for a wave scattered by a 38 mm thickness slab. The fundamental frequency spreads over the coda wave but the harmonics are located around the arrival time ($170 \mu s$).

208 observed. Moreover, the elastic mean free path is the same in nonlinear regime and in linear
 209 regime: (4.65 ± 0.16) mm and (4.65 ± 0.10) mm, respectively.

210 From these results, it can be concluded that, despite the presence of a nonlinear regime,
 211 the first and second harmonics of the coherent wave propagate independently from each
 212 other, as happens in a linear regime. However, the harmonics that spread over the coda
 213 wave are not considered. It can be noticed from the spectrograms computed for the coherent
 214 wave. In figures 4c and 4d, the spectrograms for $L = 15, 38$ mm with $V_{in} = 285$ V, are shown.
 215 Unlike those shown in IV A, the harmonics are mainly concentrated around $170 \mu s$. This
 216 fact leads to wonder if the incoherent wave and its harmonics, also propagates as in a linear
 217 regime. With this question in mind, we perform a virtual time reversal approach, which
 218 include the harmonics of both the coherent and the incoherent wave.

219 V. THE VIRTUAL TIME REVERSAL APPROACH

220 There are different ways to describe the time reversal process. In this work, a description
 221 based in a linear time-invariant system is presented. Let's $s(x, t)$ be the wavefield at the x -
 222 axis and let's choose $x = 0$ as the focal position. On one hand, the *real time reversal* process
 223 consists on time reversing and re-emitting the signal $s(0, t)$. Then, a focused wave at $x = 0$
 224 is achieved. On the other hand, the *virtual time reversal* process consists on computing the
 225 following cross correlation:

$$\gamma_c(x, t) = s(x, t) \star s(0, t) \tag{3}$$

226 where $\gamma(x, t)$ is the cross correlated field. This procedure approaches to a real time reversal
 227 process if the signal emitted from the transducer is a very short signal, being the parity of
 228 $\gamma(x, t)$ the same of $e(t)$ ¹⁴.

229 The operation proposed in equation 3 was performed by measuring the acoustic field on
 230 the x -axis and sweeping between $x = -10$ mm and $x = +10$ mm. Then, the field $\gamma_c(x, 0)$ is
 231 computed. Its envelope is shown in a dB color-scale (where the reference is the maximum
 232 amplitude) in figures 5a, 5b and 5c for $L = 15, 38, 60$ mm, respectively. The voltage was

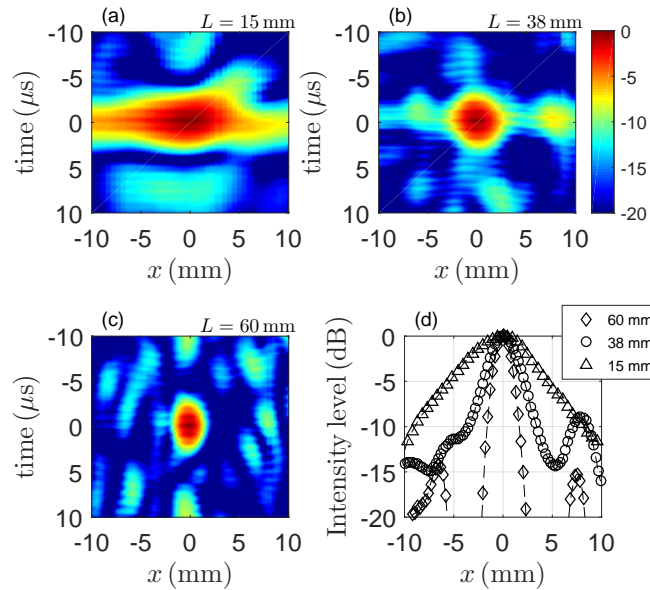


FIG. 5. Color online. Space-time distribution of the acoustic intensity level (in dB) of the virtual time reversal signal obtained with slabs of thicknesses (a) 15 mm, (b) 38 mm and (c) 60 mm. As the images show, the focal width decreases as L increases. (d) Intensity level in dB of $\gamma_c(x, 0)$ obtained with slabs of thicknesses 15 mm (triangle), 38 mm (circle) and 60 mm (diamond). The -3 dB focal widths decrease as the thickness of the multiple scattering medium is increased. $V_{in} = 285$ V for each acquisition.

233 $V_{in} = 285$ V. The time scale is shifted in such a way that the focal time is $t = 0$. It is clear
 234 that the wave is focused in both time and space. In addition, it can be noticed that the
 235 focal width is reduced as the thickness of the slab is increased. This occurs due to the loss
 236 of correlation between the spectral components of $s(0, t)$ and $s(x \neq 0, t)$ as a consequence
 237 of the multiple scattering. This result is well known in the linear wave theory¹⁰. However,
 238 here it is shown for nonlinear waves. In figure 5d the intensity level of the cross correlated
 239 field is plotted at $t = 0$. The narrowing of the focal spot can be quantified by measuring the
 240 width Δx at -3 dB. For a slab 15 mm thick, the focal width is 7.1 mm and, for a thickness
 241 of 60 mm, it reduces to 1.8 mm.

242 The fundamental and the second harmonics of γ_c are also studied along the $x -$ axis to
 243 evaluate how the presence of the second harmonic affects the cross correlated field. Consid-
 244 ering a window of $5 \mu\text{s}$ (5 cycles) around $t = 0$, the spectrum of each signal is computed by a
 245 FFT algorithm. Figures 6a and 6b show the intensity level of these harmonics in a dB scale
 246 (taking as reference the maximum of each data series). The focal width of the first harmonic
 247 Δx_1 (fig. 6a) is reduced from 7.5 mm to 1.9 mm as the thickness of the slab is increases
 248 from 15 mm to 60 mm. Moreover, the focal width of the second harmonic Δx_2 (fig. 6b) is
 249 reduced from 5.6 mm to 1.0 mm. In figure 6c, Δx , Δx_1 and Δx_2 are plotted as a function of
 250 L . Notice that for a given thickness L , it is satisfied that $\Delta x_2 < \Delta x < \Delta x_1$. This is clearly
 251 observed for $L = 8$ mm, but remains true in the whole range studied (although is harder to
 252 perceive in the figure).

253 The observation of the last paragraph shows that the second harmonic, and therefore the
 254 nonlinearity, contributes to reduce the focal width. To analyze this fact, the experiment

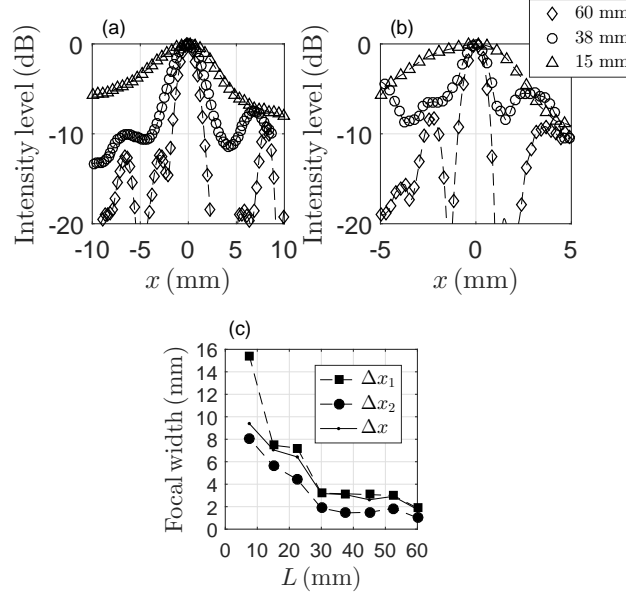


FIG. 6. Intensity level in dB of (a) the first harmonic and (b) the second harmonic at $t = 0$. (c) -3 dB focal width of the first and second harmonic (Δx_1 and Δx_2 , respectively) and for the complete signal (Δx) as a function of L . The focal width decreases as L increases and, for a given thickness, it is narrower at the second harmonic. $V_{in} = 285$ V for each acquisition.

is repeated by exciting the transducer with applied voltages of 32 V and 158 V. In figure 7a, Δx is plotted against L for the three applied voltages. For $L = 8$ mm the focal width decreases from 12 mm to 9.4 mm as the applied voltage is increased from 32 V to 285 V. When the slab is thicker this difference is less noticeable but, in general, the focal width tends to decrease as V_{in} increases. The explanation of this fact is delayed to the end of the section.

In figure 7b Δx_1 is plotted against L for the three voltages. There is no noticeable difference in the focal width as the applied voltage grows. The same behavior appears in the second harmonic. In figure 7c, Δx_2 is plotted against L only for voltages of 158 V and 285

264 V (at 32 V this harmonic is negligible). Again, the shift in the focal width as the applied
 265 voltage increases remains very small.

266 It is clear from the experiments that the behavior of the fundamental and the second
 267 harmonic do not depend of the applied voltage. Moreover, as happens in a linear regime¹⁰,
 268 the focal width of both harmonics decreases to a limiting value if the thickness of the multiple
 269 scattering medium is increased. In addition, the focal width of the second harmonic is
 270 narrower than the focal width of the fundamental one, in connection to the better resolution
 271 given by a lower wavelength. These results are consistent with a decoupling between the

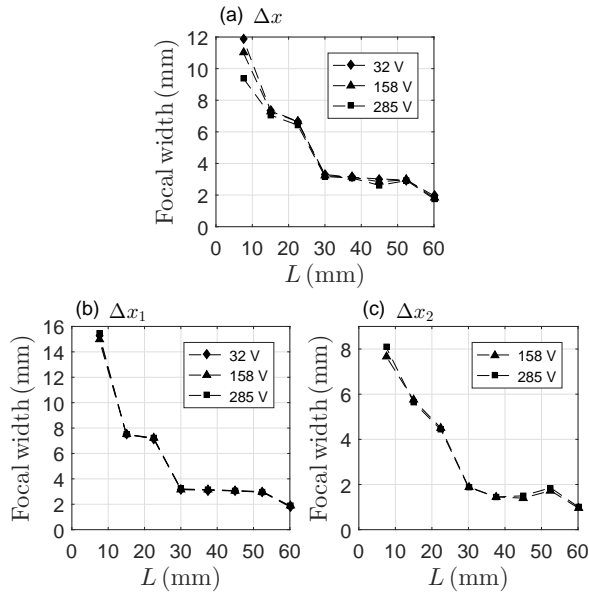


FIG. 7. -3 dB focal width of (a) the complete signal Δx , (b) the first harmonic Δx_1 and (c) the second harmonic Δx_2 . At 32 V the amplitude of the second harmonic is very low so its focal width is not shown. For a given L , Δx decreases as V_{in} increases. This behavior is not seen on each harmonic separately.

272 scattering and the nonlinear phenomena but, before state a conclusion, the behavior of the
 273 whole wave and the time reversal process are analyzed with more detail.

274 Focusing by time reversal through a multiple scattering medium is possible due to the
 275 medium acting like an acoustic lens, whose effective aperture increases as its thickness do it
 276 so. This is because the multiple scattering allows to acquire components of the wavevector
 277 that, otherwise, would be lost to the sides². In this way, and considering the multiple
 278 scattering medium as a lens with aperture D and focal length F , an estimation of the focal
 279 width can be given by:

$$\Delta x = \frac{\lambda F}{D} \quad (4)$$

280 where λ is an effective wavelength. Since there are at least two frequencies involved in
 281 the emission (the first and second harmonics) the effective wavelength can be calculated by
 282 performing the following weighted average:

$$\lambda = \sqrt{\alpha_1^2 \lambda_1^2 + \alpha_2^2 \lambda_2^2} \quad (5)$$

283 where $\lambda_1 = c_w/f_0$ is the wavelength associated with the central frequency and $\lambda_2 = c_w/2f_0$
 284 the wavelength of the second harmonic. α_1 and α_2 are the weights of each frequency in the
 285 spectrum. This average is calculated in a discrete way, based on the work of J. Brum et
 286 al¹⁵. In equation 5 more harmonics can be included but they do not produce appreciable
 287 changes in the result. The relation 4 can be applied on the first harmonic, so that $\frac{F}{D} = \frac{\Delta x_1}{\lambda_1}$.
 288 Substituting this ratio in the equation 4 yields:

$$\Delta x = \frac{\lambda}{\lambda_1} \Delta x_1 \quad (6)$$

289 This substitution is reasonable as long as the thickness of the multiple scattering medium
 290 is larger than the mean free path and the F/D ratio is not related to the frequency nor
 291 the thickness of the slab. With the experimental values of α_1 and α_2 the value of λ was
 292 calculated. Together with the experimental value of Δx_1 , Δx was calculated with the aid of
 293 equations 5 and 6. The result is shown in figure 8, where the experimental focal width and
 294 the estimated focal width of the whole signal are plotted against L ($V_{in} = 285$ V). Notice
 295 that, for $L > 30$ mm, the estimated values are very close to the experimental ones.

296 To show that the results are consistent, one more calculation is performed. The focal
 297 width reached is, in average, 2.7 mm for $L > 30$ mm, which yields an 1.4 mm effective
 298 wavelength. Using these values in equation 4, the F/D ratio yields 1.9. If $F = 250$ mm is

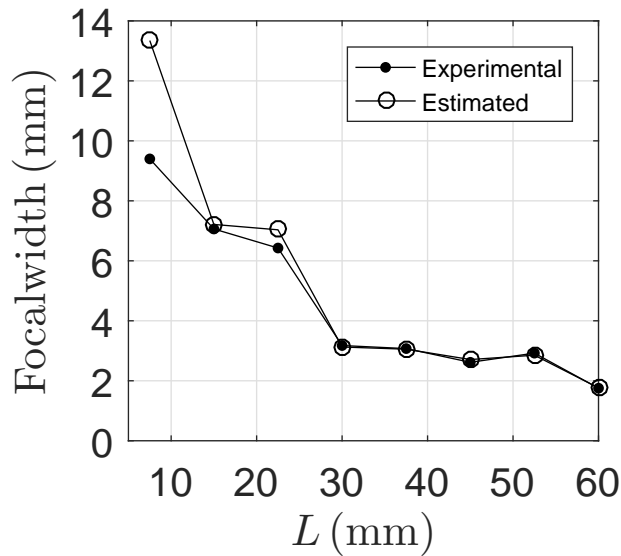


FIG. 8. Comparison between the experimental value of Δx ($V_{in} = 285$ V) and its estimation obtained by computing an effective wavelength. Both curves show a good agreement for $L > 30$ mm.

299 assumed (distance between the transducer and the hydrophone), the slab can be considered
300 as a lens of aperture $D = 132$ mm. This value is close to the length of the slab (140 mm on
301 x -axis).

302 From the latter consideration, it can be explained why the focal width of the whole wave
303 decreases as V_{in} is increased. As can be deduced from equation 5, the effective wavelength is
304 smaller the more frequencies are present in the wave, which gives a lower focal width. Then,
305 the nonlinear harmonics of the wave contribute to reduce the focal width. As a result, in a
306 linear regime, the focal width should be greater than in a nonlinear regime.

307 Finally, the study of this section shows that the behavior of the whole wave together
308 with the first and the second harmonic can be explained with elements of the linear theory.
309 Then, we can assert that the wave propagates through the slab as in a linear regime.

310 VI. DISCUSSION

311 Throughout the work, it was presented evidence of the decoupling between the multiple
312 scattering and the nonlinear phenomena for a particular system. This means that the
313 propagation of the harmonics through the multiple scattering medium is essentially linear,
314 despite a nonlinear phenomenon is required for the second harmonic to be generated. Under
315 these conditions, it is possible to take advantage of the spectral richness of the nonlinear
316 wave to study the response of a multiple scattering medium in a frequency range greater
317 than that which can be covered in a linear regime.

318 The analysis leads to a new question: is there a condition on the emitted wave or in the
319 slab construction where an interaction between nonlinear phenomena and multiple scattering

320 can be observed? To answer this, two parameters must be considered: the amplitude of
321 the emitted wave and the density of the multiple scattering medium. As was mentioned
322 in III, these parameters are related to ϵ and η and the equation 1 is valid in conditions
323 where $\eta\epsilon^2$ can be neglected. For $\eta\epsilon^2$ being in the order of η , the amplitude of the wave
324 should be increased at least five orders of magnitude. This is not possible with the available
325 amplification system. Then, equation 1 is a good model for the experiments proposed here.
326 From this equation, it was suggested that the wave satisfies a linear scattering equation
327 if ϵ^2 is negligible compared to η . For ϵ^2 to be of the same order of magnitude as η , the
328 latter must be reduced by at least eight orders of magnitude. On one hand, this can be
329 achieved by reducing the total area occupied by the scatterers by the same amount. One
330 possibility is to dilute the medium by reducing the density of scatterers. However, the
331 distance between them would be much greater than the wavelength and there would not
332 be multiple scattering. As an alternative, the diameter of the scatters could be reduced
333 at least four order of magnitude, but the construction of the slab would be impossible (at
334 least in the way it was done in this work). On the other hand, copper could be replaced by
335 another material. It is needed that the wave speed c_n of the new material be close to the
336 wave speed in water. Precisely, their relative difference $\left| \frac{c_n - c_w}{c_w} \right|$ must be in the order of 10^{-8} .
337 Although the experiments presented in this work were performed in specific conditions, based
338 on the orders of magnitude computed above, it can be concluded that multiple scattering
339 phenomena will not interact with nonlinear phenomena in a wide range of conditions. In
340 a future work, the possibility of achieving an interaction between multiple scattering and
341 nonlinear phenomena will be investigated attempting to find a different scattering medium.

342 **VII. CONCLUSION**

343 It has been shown that the time reversal focusing improves if the thickness of the multiple
344 scattering medium increases. The results reported here show that this is true even for
345 nonlinear waves. This fact is consistent with an absence of interaction between nonlinear
346 and multiple scattering phenomena and it suggests the possibility of using the virtual time
347 reversal focusing technique as a coupling test between these phenomena.

348 The nonlinear propagation introduces higher frequencies into the wave spectrum. Based
349 on the behavior of the first and second harmonics two conclusions can be pointed out:

350 a) the expansion of frequency components of the wave improves the quality of focusing
351 by time reversal;

352 b) the focal width of the second harmonic is narrower than the focal width of the funda-
353 mental. Therefore, by taking advantage of the second harmonic in a time reversal process,
354 it is possible to obtain resolutions below the value of the central wavelength.

355 In this work, focusing by virtual time reversal of nonlinear waves was studied. The
356 results reported may eventually not agree with a real time reversal experiment. However,
357 in conditions where the nonlinear effects are decoupled from the multiple scattering effects,
358 the harmonics propagate independently from each other, obeying a linear wave equation.
359 Therefore, it is expected that the wave focusing of a real time reversal experiment agree
360 with the results reported here.

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